Up-to-date city maps for modeling, planning, and assistive technologies

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The Goal: Map, assess, and monitor all the infrastructure



Distributed data collection

Imaging is done with a portable Android device mounted inside a vehicle.



Can be used in service vehicles no special personnel required for data collection

Obtain time-stamped images, GPS, accelerometer, compass and gyroscope measurements city-wide, on a regular basis







Stop sign inventory and assessment



Level 2

Commercialization:



using smartphones.

Delivers road damage

Accomplishments:

- Fall 2018: 75+ customers in 15 states and 2 countries
- American Society of Civil Engineers Innovation Contest Overall Winner, 2018
- First runner-up in the 2017 Le Monde International Smart Cities Competition



RoadBotics



Follow-on Research

Training with simulation





Training of fire hydrant detection on synthetic images from CARLA

Testing on real road images from Pittsburgh

Parking detection



Detect parked cars. This will be used as input to optimize parking regulations and fees.

Related Research Landslide prediction and analysis



Use deep learning and 3D reconstruction to predict, detect, and analyze landslides.

Edge Computing



Preliminary results: 0.42 (average precision, 0.5 IOU)

Do the detection on the vehicle itself and only send

pertinent information over the band-width limited network

Acknowledgements

This research was supported by the T-SET University Transportation Center sponsored by the US Department of Transportation under Grant No. DTRT12-G-UTC11, the Hillman foundation, the Buhl foundation, and the NSF under Award No. CNS-1446601.